# DYNAMIC PROGRAMMING FOR OPTIMAL ALLOCATION OF MAINTENANCE RESOURCES ON POWER DISTRIBUTION NETWORKS

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# Summary



- 2 Motivation
- Optimisation Model
- Heuristic Method
- 5 Dynamic Programming
- 6 Experiments
- Conclusions

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# **Radial Network**

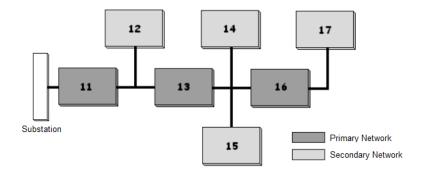


Figure: Reference Radial Network

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#### **Failure Rates**

$$\lambda_{s}^{t} = \lambda_{s} + \sum_{e \in E_{s}} \lambda_{e}^{t}$$
$$\lambda_{e}^{t} = \lambda_{e}^{(t-1)} \sum_{n \in N_{k_{e}}} \delta_{k_{e}n} x_{en}^{t}$$
$$\sum_{n \in N_{k_{e}}} x_{en}^{t} = 1,$$

#### where:

- $\lambda_e^t$  is the failure rate for equipment *e* in the period *t*;
- λ<sub>e</sub><sup>(t-1)</sup> is the failure rate for equipment e in the last year or the initial failure rate for equipment e(t = 1);
- N<sub>ke</sub> is a set of all preventive maintenance actions;
- $\delta_{k_e n}$  is the failure rate multiplier for equipment  $k_e$  for action level n;

•  $x_{en}^t$  is a boolean decision variable denoting whether the equipment *e* received  $(x_{en}^t = 1)$  or not  $(x_{en}^t = 0)$  maintenance level *n* in the period *t*.

#### **Reliability Constraints**

Thus, the SAIFI (The System Average Interruption Frequency Index) of system can be calculated:

$$SAIFI^{t} = \frac{1}{N_{T}} \sum_{s \in S} \lambda_{s}^{t} N_{s},$$

where:

- S is the set of all sections;
- $\lambda_s^t$  is failure rate of section *s* in the period *t*;
- *N<sub>s</sub>* is the number of customers into section *s*;
- $N_T$  is the number of all customers into the Network.

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#### **Optimisation Problem**

$$\min_{\substack{x_{en}^{t} \\ k_{en}^{t}}} \sum_{t=1}^{HP} \left\{ \sum_{e \in E} \left[ \sum_{n \in N_{k_{e}}} (p_{k_{en}} x_{en}^{t}) + \lambda_{e}^{t} c_{k_{e}} \right] \times \alpha_{t} \right\}$$

$$s.t: \quad SAIFI^{t} \leq SAIFI_{perm} \quad \forall t = 1, ... HP,$$

#### where:

- *E* is a set that contains all the equipment which can receive preventive maintenance;
- SAIFIperm is the maximum permitted for SAIFI;
- $p_{k_en}$  is the cost for action preventive level *n* for equipment  $k_e$ ;
- c<sub>ke</sub> is the cost for action corrective level for equipment ke;
- $\alpha_t$  is a parameter which is related to each period.

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# **State Space Search**

#### Example 30 equipments and HP=3

Chosen\_action(**S**,**S**')

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- Depth Search with Simulated Annealing
  - Constructive Heuristic
  - Depth Search
  - Simulated Annealing

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#### **Knapsack Problem on Dynamic Programming**

$$F_{n}(b) = \max \sum_{\substack{j=1 \ n}}^{n} c_{j} x_{j}$$
  
s.t. 
$$\sum_{\substack{j=1 \ x_{j} \in \{0, 1\}, j = 1, ..., n}}^{n} a_{j} x_{j} \leq b$$

#### Where:

 $\sum_{j=1}^{n} c_j x_j$ : total value of the selected elements to the Knapsack;  $\sum_{j=1}^{n} a_j x_j$ : total volume of the selected elements to the Knapsack.

#### The aim is get *n*-th value as from basic cases

Get 
$$F_n(a_0)$$
  
Where  $F_k(a) = \max \{F_{k-1}(a), F_{k-1}(a - a_k) + c_k\}$   
With  $F_0(a) = 0 \ \forall a$ 

To determine the optimal solution:

- Create an indicator p<sub>k</sub> that is equal 0 if F<sub>n</sub>(b) = F<sub>n-1</sub>(b), and 1 otherwise.
- Analyzes all indicators from  $p_n$  up to  $p_1$ . If the indicator  $p_k = 0$  then  $x_k^* = 0$ , else  $x_k^* = 1$ .

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### **Problem Adapted**

$$\begin{array}{ll} \textit{Get} & \textit{F}_n(\textit{M}_0) \\ \textit{Where} & \textit{F}_k(\textit{M}) = \min\left\{\textit{F}_{k-1}(\textit{M}) + \textit{Cp}_k + \left(\lambda_k^{\textit{cm}} \times \textit{Cc}_k\right), \\ & \textit{F}_{k-1}(\textit{M} - \textit{v}_k) + \left(\lambda_k^{\textit{sm}} \times \textit{Cc}_k\right)\right\} \\ \textit{With} & \textit{F}_0(\textit{M}) = 0 \; \forall \textit{M} \\ \end{array}$$

#### Where:

 $Cp_k$  is the maintenance preventive cost for equipment k;  $Cc_k$  is the maintenance corrective cost for equipment k;  $\lambda_k^{cm}$  is the failure rate for equipment k which was received preventive maintenance;

 $\lambda_k^{sm}$  is the failure rate for equipment k which was not received preventive maintenance;

 $v_k$  is the volume of the equipment k which was selected to the knapsack M.

#### Important Steps of the Algorithm Developed

- Calculating the boundary given by the reliability constraints;
- 2 Calculating the volume of equipments:

$$\mathbf{v}_{k} = \delta \times (\lambda_{k}^{sm} - \lambda_{k}^{cm})$$

Olicial Calculating knapsack size:

$$M = \delta \times (SAIFI_{perm} - SAIFI_{min})$$

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# Pseudocode

Pseudocode Knapsack Problem (n,M)

- 1: Calculate SAIFI<sub>min</sub> SAIFI<sub>max</sub>
- 2: **Calculate**  $v_k \forall k = 1..n$
- 3: *knapsack(n,M)*→ *p*
- 4: **Calculate**  $F_0(M) = 0 \forall M$
- 5: **For** k = 1..n **do**
- 6: **For** m = 1..M **do**

7: 
$$F_k(M) = \min \{F_{k-1}(M) + Cp_k + (\lambda_k^{cm} \times Cc_k), F_{k-1}(M - v_k) + (\lambda_k^{cm} \times Cc_k)\}$$

- 8: End For
- 9: End For
- 10: **OptimalSolution**(p,M) $\rightarrow$  S **Return:** S

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# **Studied Cases**

#### Instances

Six intances were created for the problem:

- 1 Instance with 30 equipments;
- 2 Instance with 50 equipments;
- 3 Instance with 100 equipments;
- 4 Instance with 150 equipments;
- 5 Instance with 300 equipments;
- 6 Instance with 400 equipments;
- All instances were executed for only one period.

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#### **SAIFI** permitted

- For each instance five values of constraints were chosen;
- Calculating via Equation:

 $SAIFI_{\alpha} = SAIFI_{min} + (SAIFI_{max} - SAIFI_{min}) \times \alpha$ 

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where  $\alpha$  is 0.2, 0.4, 0.6, 0.8 and 1.0.

#### **Equipments Values**

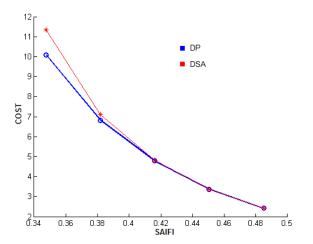
Тіро	CMC	CMP	Mtx MP	CSM	Mtx SM	TF Initial
Cable	0.06	0.03	0.92	0	1.08	0.02
infrastructure 1	0.94	0.47	0.79	0	1.26	0.05
infrastructure 2	0.94	0.47	0.79	0	1.26	0.05
Post 1	14.5	7.25	0.69	0	1.2	0.001
Post 2	14.5	7.25	0.69	0	1.2	0.001
Regulator	16	8	0.89	0	1.12	0.029
Recloser	1.2	0.6	0.91	0	1.28	0.015
Primary Pruning	2.05	1.025	0.95	0	1.51	0.05
Secondary Pruning	1.05	0.525	0.95	0	1.51	0.05
Transformer	1.692	0.846	0.95	0	1.51	0.01

# **Results**

Instance with 30 equipments:

	DP		DSA		
	Cost	Time	Cost	Time	Profit
SAIFI	(x 1000)	(S)	(x 1000)	(s)	(%)
0.3476	10.0766	0.1560	11.3455	1.2012	11.14
0.3819	6.8217	0.7020	7.1146	0.2964	4.11
0.4163	4.7854	1.6224	4.8152	0.2184	0.61
0.4506	3.3699	2.8548	3.3699	0.1404	0
0.4849	2.4145	4.6332	2.4145	0.1716	0

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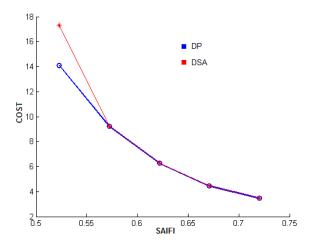
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# **Results**

Instance with 50 equipments:

	DP		DS		
	Cost	Time	Cost	Time	Profit
SAIFI	(x 1000)	(S)	( x 1000)	(S)	(%)
0.5227	14.0922	0.3276	17.3370	1.2480	18.71
0.5722	9.2147	1.4196	9.2326	0.3120	0.19
0.6216	6.2706	3.5256	6.3004	0.2964	0.47
0.6710	4.4370	6.3804	4.4370	0.4060	0
0.7204	3.4518	10.1245	3.4518	0.3276	0

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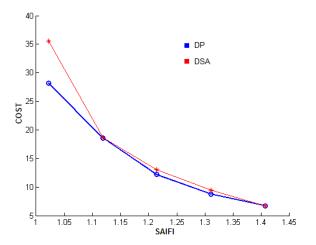


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# **Results**

#### Instance with 100 equipments:

	DP		DSA		
	Cost	Time	Cost	Time	Profit
SAIFI	(x 1000)	(S)	(x 1000)	(S)	(%)
1.0221	28.1844	0.9672	35.5105	2.0124	20.63
1.1183	18.5903	4.9140	18.6201	3.2136	0.16
1.2144	12.1651	12.7141	12.9892	1.0452	6.34
1.3106	8.7846	22.1521	9.4412	0.7020	6.95
1.4068	6.6941	35.0690	6.7239	0.9204	0.44

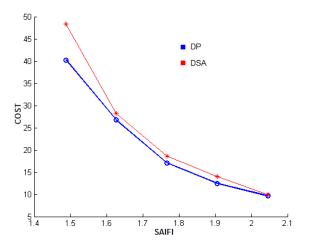


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# **Results**

#### Instance with 150 equipments:

	DP		DS		
	Cost	Time	Cost	Time	Profit
SAIFI	(x 1000)	(S)	(x 1000)	(S)	(%)
1.4878	40.2492	2.1060	48.3821	11.7157	16.80
1.6272	26.7334	10.7017	28.2550	2.1216	5.38
1.7665	17.1013	25.6564	18.5819	6.6456	7.96
1.9059	12.4963	47.1747	14.0188	8.3461	10.86
2.0452	9.6598	75.2237	9.9876	13.3849	3.28

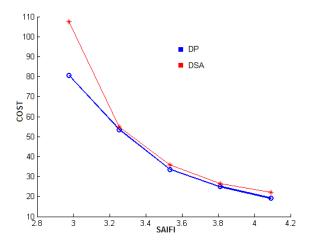


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# **Results**

#### Instance with 300 equipments:

	DP		D	]	
	Cost	Time	Cost	Time	Profit
SAIFI	(x 1000)	(s)	(x 1000)	(s)	(%)
2.9757	80.4985	11.5285	107.6273	290.8254	25.20
3.2543	53.4667	52.2447	54.9088	250.8466	2.61
3.5330	33.5628	124.7384	35.8796	1295.7478	6.45
3.8117	24.9627	242.0356	26.6641	1681.9546	6.38
4.4068	19.1697	398.0834	22.2148	231.5548	13.70

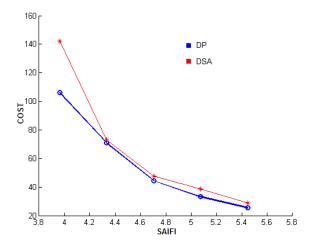


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# **Results**

#### Instance with 400 equipments:

	DP		D	]	
	Cost	Time	Cost	Time	Profit
SAIFI	(x 1000)	(s)	(x 1000)	(s)	(%)
3.9625	106.2709	25.7558	142.0483	7258.3457	25.18
4.3336	70.8304	111.8215	72.9871	705.4124	2.95
4.7046	44.3515	255.7480	47.6116	2240.4517	6.84
5.0757	33.1114	446.8805	38.4557	1290.7457	13.89
5.4468	24.4373	712.9090	28.6017	5070.5072	14.55



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#### Conclusions

- In all instances the dynamic programming algorithm achieved the best results;
- In small instances, the state space search algorithm achieved good results when the constraints were looser, but the results deteriorates when the number of equipment grows;
- Dynamic programming has maintained a standard result on the all values of time achieved, increasing as the number of equipments grows.
- The same not happened with the state space search algorithm, increasing a lot of the computational time.

### **Future Works**

As Future Works:

- Increase the period of optimisation;
- The development of equations dividing the problem in 2<sup>*HP*</sup> subproblems.

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### Acknowledgements

- CNPq
- CAPES